

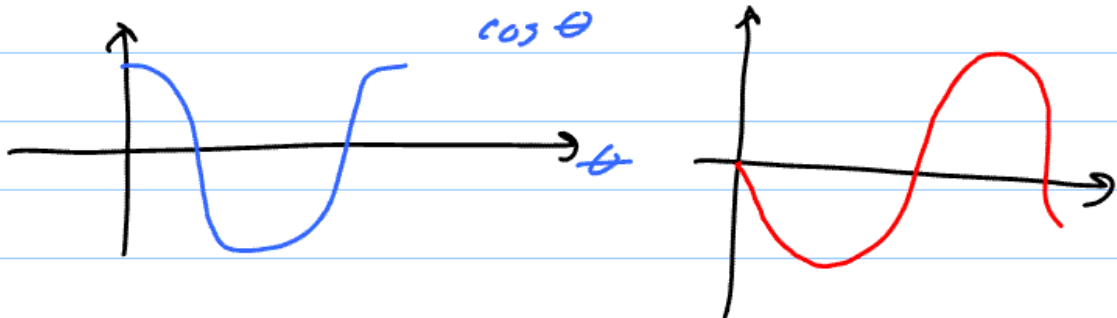
## PHY138 - Mechanics - Class 8 - Oct 4/06

Some Math

MAT135 gets to  
this week of  
Oct 30.

Derivatives of trig functions

$$\frac{d \sin \theta}{d \theta} = \cos \theta$$



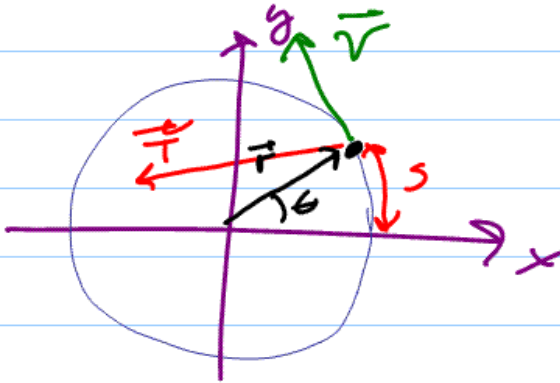
$$\frac{d \cos \theta}{d \theta} = -\sin \theta$$

§7.5. Fictitious Forces

Inertial (non-accelerating) Frames

No friction forces.

### §7.6 - Nonuniform $\odot$ Motion



$$\vec{T} = T_r \hat{r} + T_t \hat{t}$$

causes speed to increase

Eqs 2.18, 2.22

$$\left\{ \begin{array}{l} s_f = s_i + v_{ti} \Delta t + \frac{1}{2} a_t (\Delta t)^2 \\ v_f = v_i + a_t \Delta t \end{array} \right.$$

Divide by r

$$\left\{ \begin{array}{l} \theta_f = \theta_i + \omega_i \Delta t + \frac{1}{2} \frac{a_t}{r} (\Delta t)^2 \\ \omega_f = \omega_i + \frac{a_t}{r} \Delta t \end{array} \right.$$

(From chapt 13) angular acceleration  $\alpha \equiv \frac{a_t}{r}$   
 "alpha"

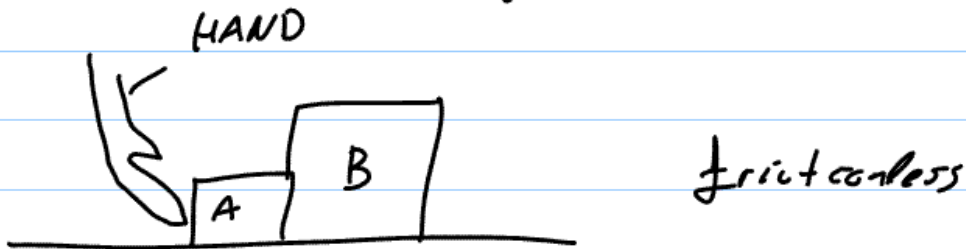
$$\theta_f = \theta_i + \omega_i \Delta t + \frac{1}{2} \alpha (\Delta t)^2$$

$$\omega_f = \omega_i + \alpha \Delta t$$

## CHAPTER 8

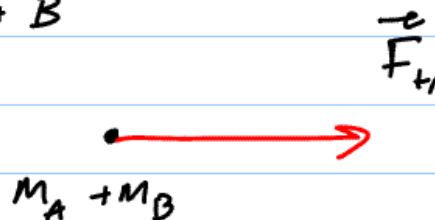
Series of examples:

For all' model as a particle  
 ignore vertical forces



System: A + B

FBD



$$\underline{a} = \frac{F_{\text{net}}}{M_{\text{tot}}} = \frac{F_H}{M_A + M_B}$$

System: B

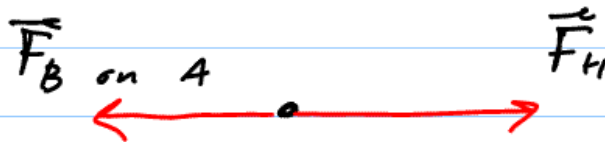
$\vec{F}_{A \text{ on } B}$



$$a = \frac{F_{A \text{ on } B}}{M_B} = \frac{F_H}{M_A + M_B}$$

$$F_{A \text{ on } B} = M_B \frac{F_H}{M_A + M_B}, \text{ right}$$

System A



$$a = \frac{F_H - F_{B \text{ on } A}}{M_A} \Rightarrow \text{algebra}$$

$$F_{B \text{ on } A} = m_B \frac{F_{L1}}{m_A + m_D}, \text{ left}$$

$$\vec{F}_{B \text{ on } A} = - \vec{F}_{A \text{ on } B}$$

3<sup>rd</sup> Law

Always true