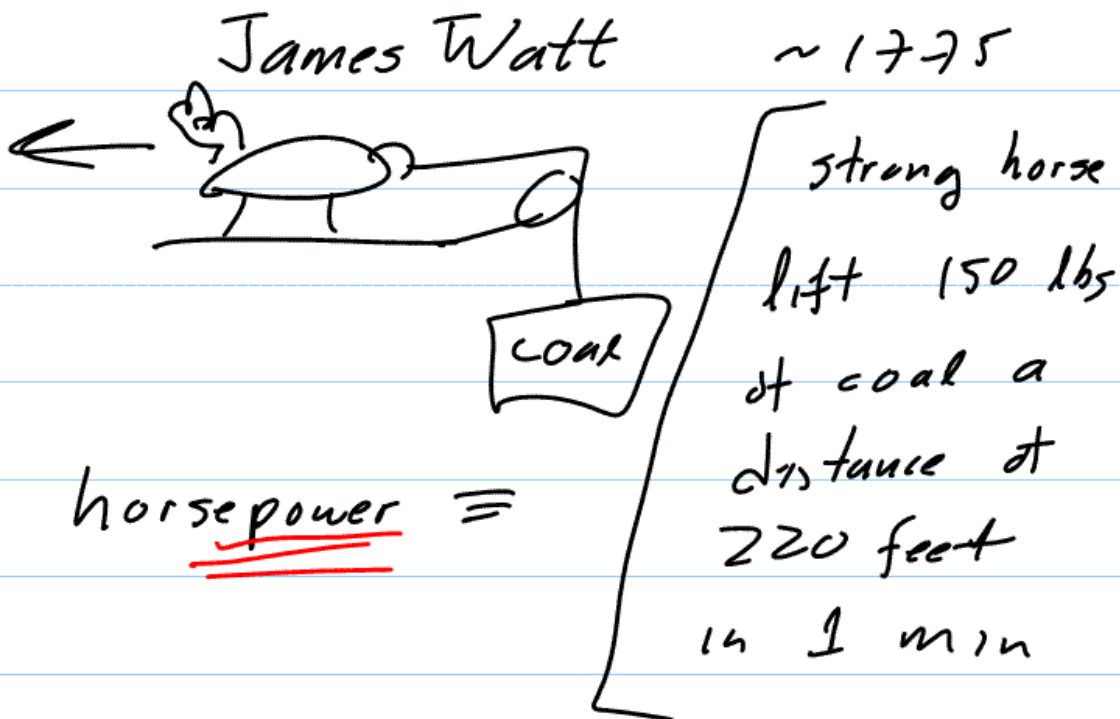


Class 12 - October 24/05

## § 11.9 Power



$$\frac{150 \text{ lbs} \times 220 \text{ feet}}{1 \text{ min}} \times \frac{1 \text{ min}}{60 \text{ sec}}$$

$$1 \text{ hp} = 550 \frac{\text{ft-lbs}}{\text{sec}}$$

$$\times \frac{4.45 \text{ N}}{\text{lb}} \times \frac{305 \text{ m}}{\text{f}} = \boxed{746 \text{ W}}$$

## Metabolism

burning energy

radiates energy!

$$\frac{dE}{dt} \sim \textcircled{1} T_{\text{surface}} - T_{\text{air}}$$

\textcircled{2} Surface area

## Equilibrium

$$b_{mr} = \frac{dE}{dt}$$

$$\rightarrow \frac{dE}{dt} \propto A \propto L^2$$

$$m = \rho V \propto L^3$$

$$L = m^{1/3}$$

$$b_{mr} \propto \frac{dE}{dt} \propto m^{2/3} \text{ "allometry"}$$

Kleiber (1932):  $bmr \propto m^{3/4}$

true 27 orders of magnitude

## CHAPT 13 - ROTATION OF RIGID BODIES

Here often models are  
not particles

### §13.1 - Kinematics

Done for particles'

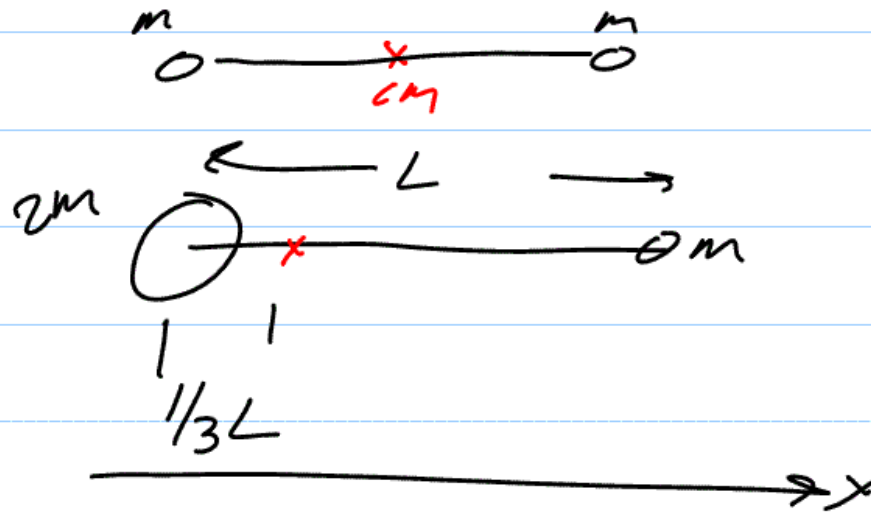
$\omega$  class 7 -

$\alpha$  class 8

Rigid body

$\omega$  } same for all  
 $\alpha$  } points

## § 13.2 - Centre of Mass



$$x_{cm} \equiv \frac{\sum_i m_i x_i}{\sum_i m_i} = \frac{1}{M} \sum_i m_i x_i$$

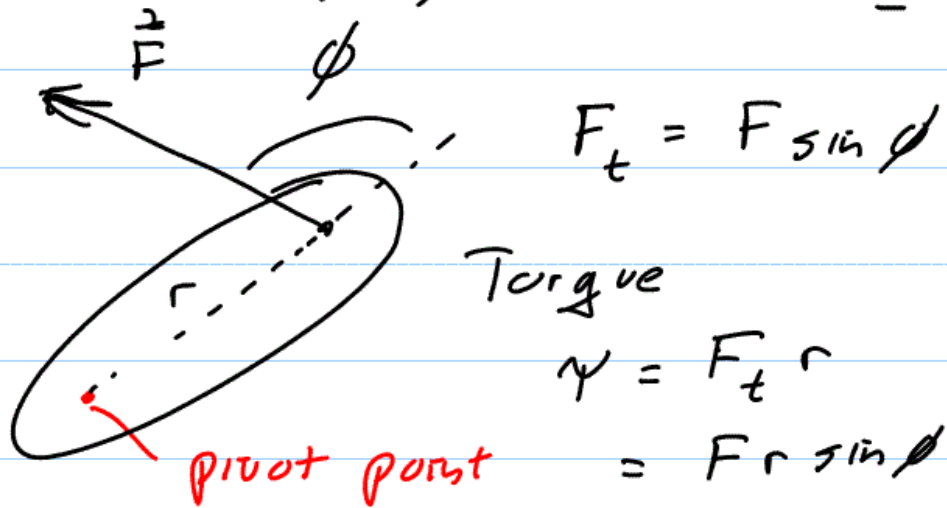
$$= \frac{1}{M} \int x dm$$

Isolated Object rotates about  
its cm

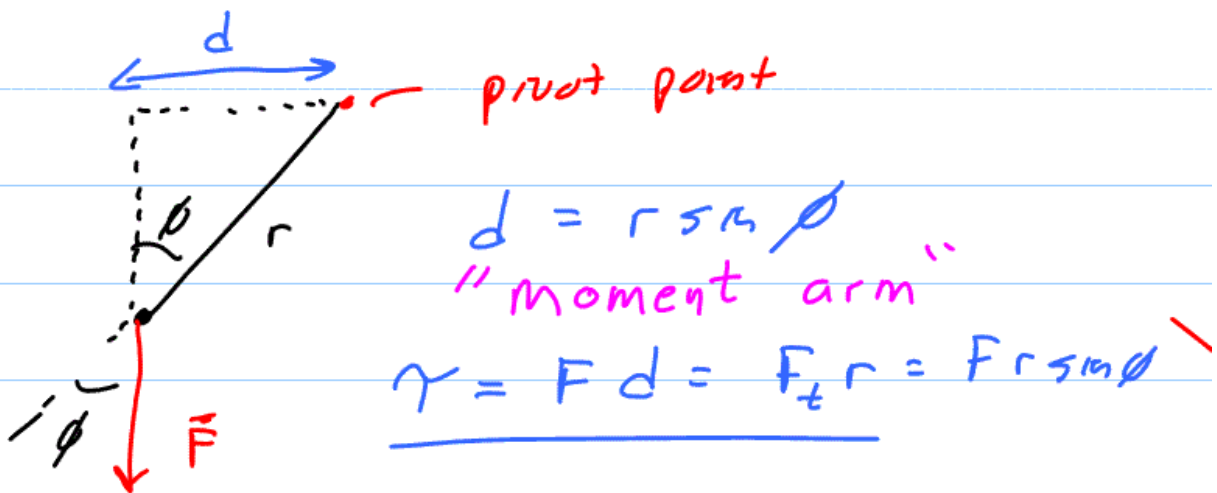
## §13.3 - Torque

$$a = \frac{F}{m}$$

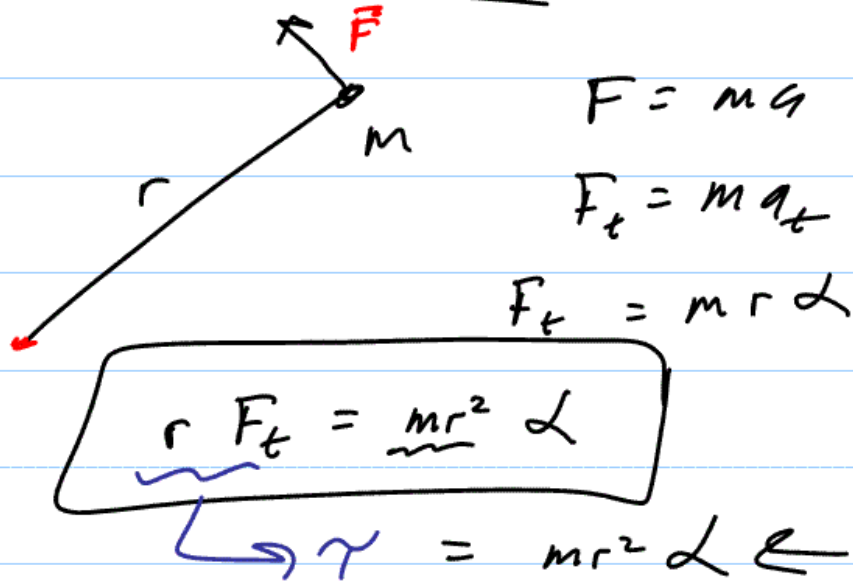
more carefully @ cause of  $\alpha$



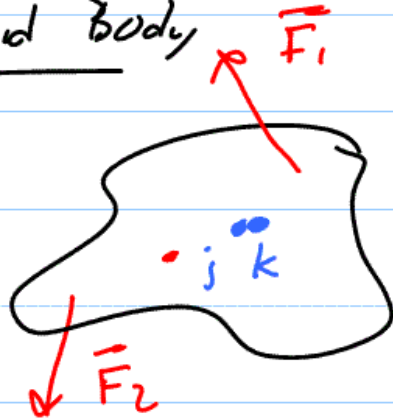
Forces on pivot point!  $\gamma = 0$



## § 13.4 - Dynamics



## Rigid Body



collection of  
 $i$  particles

$$\tau_i = M_i r_i^2 \alpha$$

$$\tau_{\text{tot}} = \sum_i \tau_i = \left( \sum_i M_i r_i^2 \right) \alpha$$

$$\tau_{j \text{ on } k} = -\tau_{k \text{ on } j} \quad (3^{\text{rd}} \text{ Law})$$

$$\sum \tau_i = \tau_{\text{tot}} = \sum_i \tau_{\text{ext}} = \left( \sum_i m_i r_i^2 \right) \alpha$$

$$\sum \tau_{\text{ext}} = \left( \sum_i m_i r_i^2 \right) \alpha$$

moment of inertia I

$$\rightarrow a = \frac{F_{\text{net}}}{m}$$

$$\alpha = \frac{\tau_{\text{net}}}{I}$$

$$I = \sum_i m_i r_i^2 = \int r^2 dm$$

$$I = cMR^2$$

$c$  - const for  
a given object  
and axis of  
rotation

$c = 0$ ! point particle

$c = 1$ ! all mass is  
distance  $R$  away  
from axis

arbitrary rigid body!  $0 < c < 1$

