

# Lecture 17

## Mechanical impedance

### Examples

References:  
Hirose Ch.6 (6.4)  
or:  
Lecture notes

### Incomplete reflection

Reflection at a free boundary and reflection at a fixed boundary are two ideal cases. In either case, reflection is complete in a sense that all energy associated with an incident wave is reflected. In practice complete reflection rarely happens.

Traveling mechanical waves can be expressed by the general function:

$$\xi(x, t) = f(x \pm c_w t)$$

**Force is proportional to the space derivative of the wave function.**

In a string:  $F = -T \sin \theta = -T \frac{\partial \xi}{\partial x}$  (transverse wave)

For a transmission line:  $F = -k_s \frac{\partial \xi}{\partial x} \Delta x = -K \frac{\partial \xi}{\partial x}$  (longitudinal wave)

Velocity wave is given by:  $v = \frac{\partial \xi}{\partial t} = \pm c_w \dot{f}(x \pm c_w t)$

If we combine force and velocity:

$$\frac{F}{v} = - \frac{(T \text{ or } K)}{\pm c_w} = \mp \sqrt{(T \text{ or } K) \rho_\ell}$$

$$c_w = \sqrt{\frac{(T \text{ or } K)}{\rho_\ell}}$$

We define Z (mechanical impedance) as:

$$Z = \sqrt{(T \text{ or } K)\rho_\ell}$$

$$F = \pm Zv \hat{i} \begin{matrix} \text{"+" for forward - going waves} \\ \text{"-" for backward - going waves} \end{matrix}$$

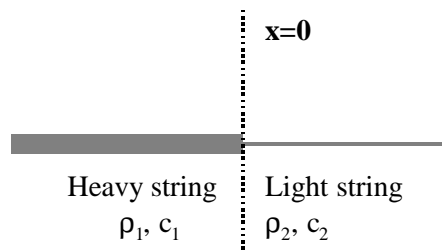
T is tension for transverse waves; K is the elastic modulus for longitudinal waves

**In mechanical waves the force  $F(x, t)$  and the velocity  $v(x, t)$  are always proportional to each other**

### Connection between two media

To illustrate incomplete reflection, we consider two strings with different mass densities  $\rho_1$  and  $\rho_2$  both subject to a common tension T. The velocities of transverse waves on each string are  $c_1$  and  $c_2$ .

At the connection between two media:



The energy flow associated with a sinusoidal wavetrain with amplitude  $\xi_0$  and frequency  $\omega = 2\pi\nu$  along a string with mass density  $\rho_1$  is given by:

$$\left\langle \frac{dE}{dt} \right\rangle = c_w \left\langle \frac{dE}{dx} \right\rangle = \frac{1}{2} c_w \rho_\ell \omega^2 \xi_0^2$$

We assume that the incident wave has an amplitude  $\xi_1$ , the reflected wave  $\xi_r$  and the transmitted  $\xi_2$ , respectively. The energy flow and the direction (little arrow) associated with:

- the incident wave is:  $\frac{1}{2} c_1 \rho_1 \omega^2 \xi_1^2 \quad \textcircled{R}$

- the reflected wave:  $\frac{1}{2}c_1\rho_1\omega^2\xi_r^2$  -

- the transmitted wave:  $\frac{1}{2}c_2\rho_2\omega^2\xi_2^2$  ⑧

From the principle of energy conservation, we must have:

$$\frac{1}{2}c_1\rho_1\omega^2\xi_1^2 - \frac{1}{2}c_1\rho_1\omega^2\xi_r^2 = \frac{1}{2}c_2\rho_2\omega^2\xi_2^2$$

or:

$$\boxed{c_1\rho_1(\xi_1^2 - \xi_r^2) = \rho_2c_2\xi_2^2}$$

The displacement at the boundary has to be continuous which means:

$$\boxed{(\xi_1 + \xi_r) = \xi_2}$$

The two simultaneous equations above allow  $\xi_r$  and  $\xi_2$  to be calculated:  
Solving these, we find:

$$\xi_r = \frac{\sqrt{\rho_1 T} - \sqrt{\rho_2 T}}{\sqrt{\rho_1 T} + \sqrt{\rho_2 T}} \xi_1 \quad \text{and :}$$

$$\xi_2 = \frac{2\sqrt{\rho_1 T}}{\sqrt{\rho_1 T} + \sqrt{\rho_2 T}} \xi_1$$

which can be re-written by using the mechanical impedance of each medium:

$$\xi_r = \frac{Z_1 - Z_2}{Z_1 + Z_2} \xi_1 \quad \text{and :}$$

$$\xi_2 = \frac{2Z_1}{Z_1 + Z_2} \xi_1$$

**The condition for the absence of wave reflection at a boundary between two media is that the impedance of the media be the same**

We can calculate now, for instance, the fraction of reflected wave energy:

$$\frac{\rho_1 c_1 \xi_r^2}{\rho_1 c_1 \xi_1^2} = \frac{\rho_1 c_1 (Z_1 - Z_2)^2}{\rho_1 c_1 (Z_1 + Z_2)^2}$$

where  $[(Z_1 - Z_2)/(Z_1 + Z_2)]^2$  is the coefficient of reflection.